



perfect in sensors.

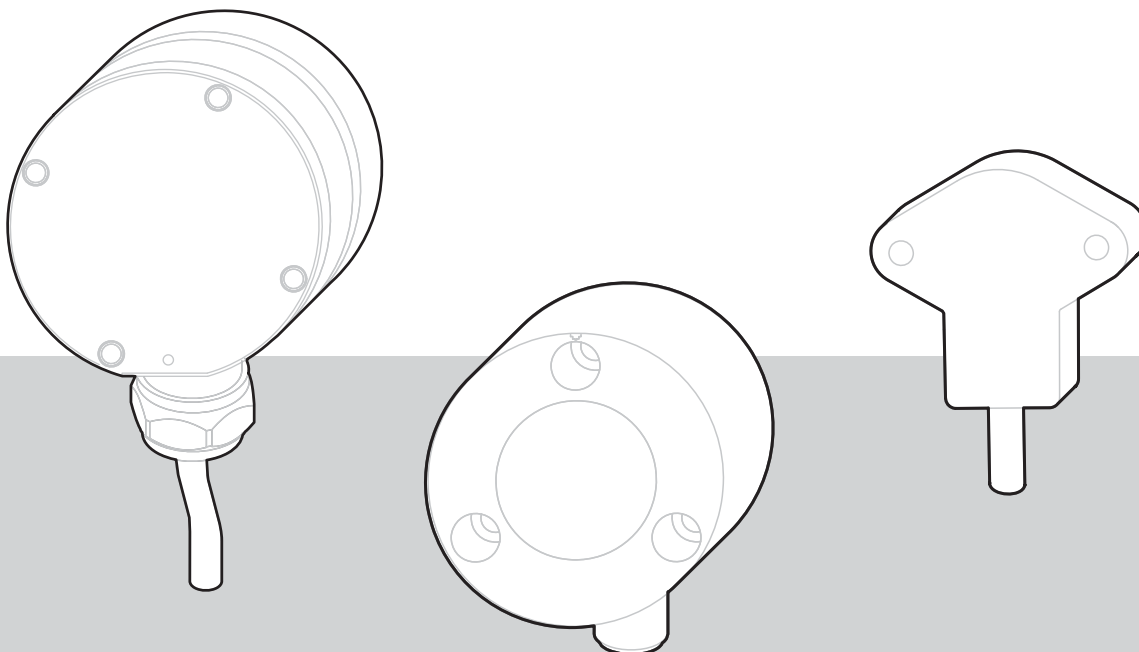
positilt[®]

PTK-CANOP, PTK-SAE J1939

Gyro-compensated Inclination Sensors

Installation and operation manual

EN



Please read carefully before installation and operation!

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1 Safety instructions

1.1 Signal words and symbols



WARNING, Risk of Injury:

Indicates a potentially hazardous situation, which, if not avoided, can result in serious injury or property damage.

⚠ DANGER

WARNING, Risk of Personal Injury or Death:

Indicates a situation that can result in serious personal injury or death if not properly avoided.

⚠ WARNING

WARNING, Risk of Personal Injury or Death:

Indicates a situation that can result in moderate personal injury or death if not properly avoided.

⚠ CAUTION

WARNING, Risk of Personal Injury:

Indicates a situation that can result in minor personal injury if not properly avoided.

NOTICE

WARNING, Risk of Property Damage:

Indicates a situation that can result in minor to major property damage if not properly avoided.

Product liability

- Disregarding the following instructions may result in malfunction, damage to property and personal injury and releases the manufacturer from product liability.

Safety regulations

- National safety regulations must be observed!

1.2 General safety instructions

⚠ WARNING

Danger of injury to the operator or damage to the property

- Connection to power supply must be performed in accordance with safety instructions for electrical facilities and performed only by qualified personnel.
- Any alteration, reconstruction or extension of the sensor is not allowed!
 - The sensor must be operated only within values specified in the datasheet.
 - The danger of personal injury and danger of property damage due to a malfunction of the sensor in machines or systems must be excluded by additional safety measures.
 - In safety-relevant applications, additional facilities must be provided for maintaining safety and preventing damage.
 - Check whether the protection class of the sensor is suitable for the application.

NOTICE

Mechanical damage or destruction of the sensor

- Do not open the sensor.
- Avoid impact and shock to the sensor.

1.3 Intended use

positilt® inclination sensors of PTK series measure inclination between $\pm 15^\circ$ and $\pm 180^\circ$ utilizing gyro-compensated MEMS technology. The angular position is converted into a standardized output. For determining measuring range, environmental compatibility and connection data of the sensor, please note the data sheet. Use the sensor as intended by operating within its specified technical data and ambient conditions.

The installation and operating instructions supplied with the unit must be respected. All maintenance and service work must be carried out. The data sheet of the respective sensor is part of this instruction manual. If not yet available, it may be requested by stating the respective model number.

The sensor must not be improperly mounted, operated or serviced. In addition, operation of the sensor in faulty condition is prohibited.

2 Transport and storage

Observe storage and transport temperatures according to the temperatures specified in the data sheet.

Max. rel. humidity 60%, dew condensation must be prevented at all times.

The device must be secured against slipping and tipping during transport.

Shipment damage

Check sensor immediately for shipment damage. In case of any damage or equipment not operating appropriately, please contact your supplier.

Shipment content

- Sensor
- Installation and operation manual


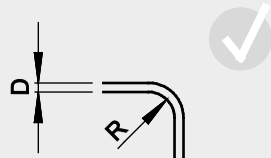
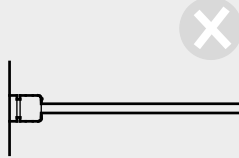

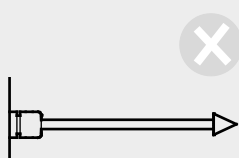
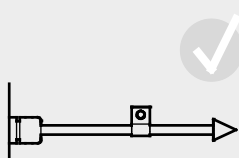



3 Installation and initial operation

Torque for fixing screws

- The specified torques and mounting methods are general recommendations and can differ according to application and operating conditions.

| Mounting method | Material | Torque [Nm] |
|--------------------------|----------|-------------|
| Screws M4 (PTK29, PTM29) | – | 1 |
| Screws M8 | – | <10 |

Installation of the sensor supply cable

| | incorrect | correct |
|--|---|--|
| Admissible bending radius of the cable must be observed: $R \sim 5 \times D$ $R \sim 10 \times D$ (underwater cable) |  |  |
| Length compensation for the cable must be observed |  |  |
| A separate cord grip for cable strain relief is recommended |  |  |
| Observe cable routing in case of splashing water, water condensation and humidity |  |   |

3.1 Electrical connection

| |
|---------------|
| NOTICE |
|---------------|

Damage or destruction of the sensor due to excessive operating voltage or mounting error

- The applied operating voltage must not exceed the value specified in the data sheet.
- Operate the sensor only within the limits specified in the data sheet.
- Connect to the power supply only by qualified personnel and in accordance with the applicable safety regulations for electrical equipment.
- Do not connect or disconnect the sensor under voltage!

Corrosion in the sensor due to moisture penetration

- Use the sensor only according to protection class.
- The mating connector should have the same protection class as the sensor, otherwise the lower protection class of the mating connector is valid.
- Avoid crossing the dew point.
- Cable outputs must be installed in such a way that no moisture can get into the cable.
- The protection class of sensors with connector output is valid only if the electrical plug is connected!

Damage of the sensor cable due to mechanical stress

- Do not twist the M12 connector inserts.
- It is important that the knurled nuts on the connectors are tightened to the correct torque for each different size of the connector:
 - M12-ASM connectors / couplings: 1.0 Nm
 - connectors / couplings of other manufacturers: according to manufacturer instruction.
- Use a torque wrench.
- Do not strain the connection cable.
- A separate cord grip is recommended.

Electromagnetic Compatibility (EMC)

Electromagnetic compatibility of positilt® inclination sensors is influenced by the sensor wiring.

NOTICE

Possible malfunction of the sensor when used in systems with highly interference-prone components such as frequency inverters

Recommended wiring:

- Use single shielded sensor cable with twisted pair conductors for power supply and signal output.
- Connect the cable shield to ground on one side of the control cabinet. Connect the shield connection over a large area using cable clamps before or at the cable entry into the control cabinet. When preassembled cables are delivered, the screen is not connected to the housing on the sensor side.
- Do not install sensor cables close to power conductors such as motor or contactor control cables (use separate cable ducts for signal and power cables).
- Install the cables in metal cable ducts which are connected to ground.

3.2 Operating temperature

| | |
|-----------------|---------------|
| positilt® PTK29 | -40 ... +85°C |
| positilt® PTK6 | -40 ... +85°C |
| positilt® PTK7 | -40 ... +85°C |

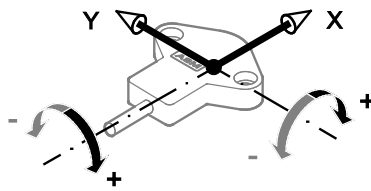
3.3 Characteristic of the linear output and mounting options

PTK29 - Characteristic of the linear output and mounting options

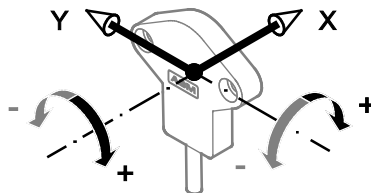
For CAN output, the mounting option can be set by the user via software.
Sensor position as shown equals 0°.

2 measuring axes

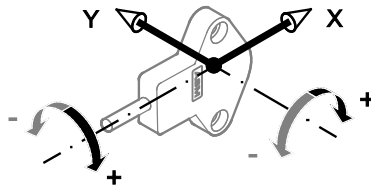
Mounting option 2A



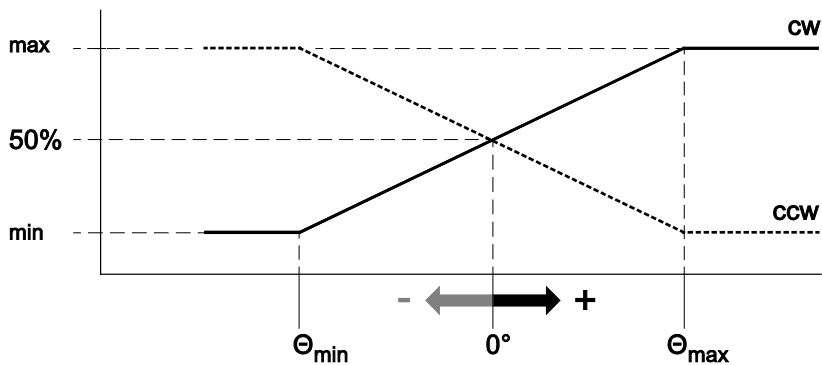
Mounting option 2B



Mounting option 2C



Output signal

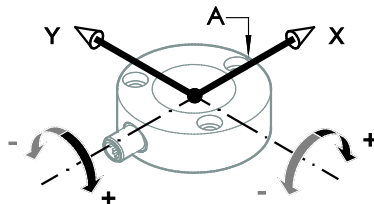


PTK6 - Characteristic of the linear output and mounting options

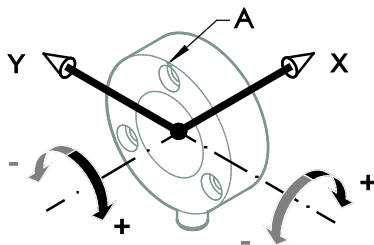
For CAN output, the mounting option can be set by the user via software.
Sensor position as shown equals 0°.

2 measuring axes

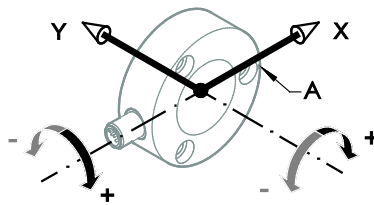
Mounting option 2A



Mounting option 2B

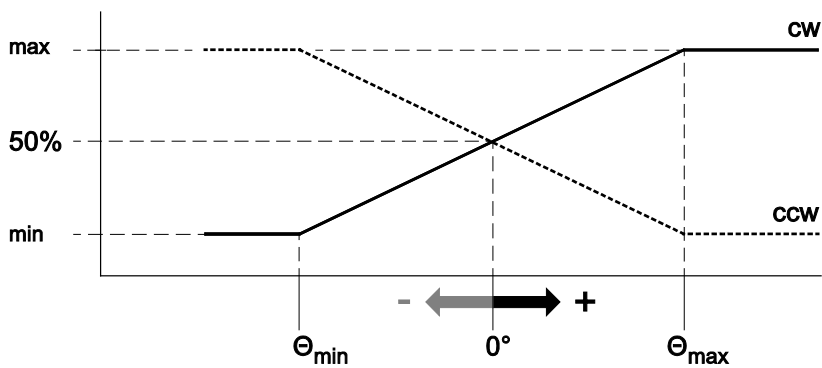


Mounting option 2C



A = Marking

Output signal

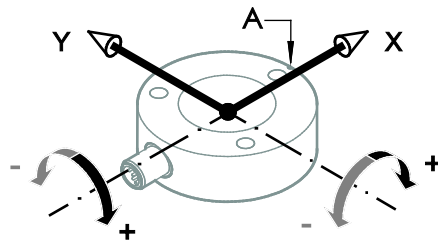


PTK7 - Characteristic of the linear output and mounting options

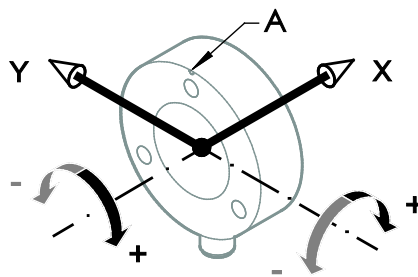
For CAN output, the mounting option can be set by the user via software.
Sensor position as shown equals 0°.

2 measuring axes

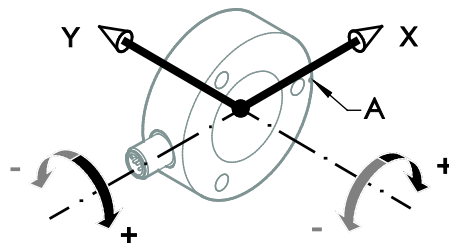
Mounting option 2A



Mounting option 2B

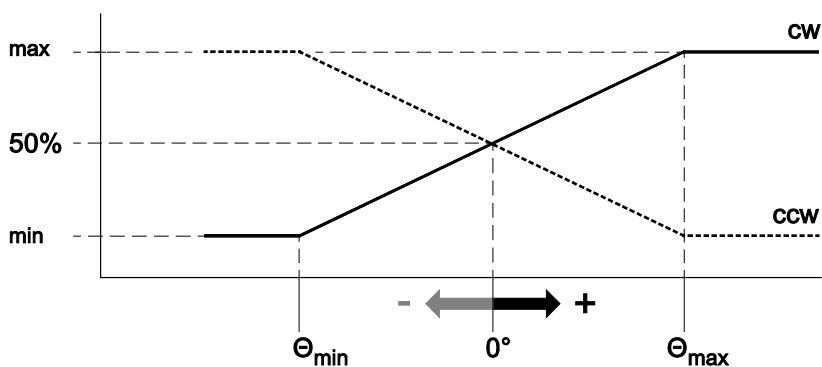


Mounting option 2C



A = Marking

Output signal



4 Maintenance and disposal

4.1 Maintenance and disposal

| |
|------------------|
| ⚠ CAUTION |
|------------------|

Opening all the positilt® sensors will cause damage and void the warranty

- Do not open the sensor.
- Due to possible risk of injury by improper handling, we strongly advise against repair attempts.

Check sensor regularly for possible damage:


| | Integrity of housing, connector, cable | Mounting elements | Fouling check |
|-----------------|--|---|----------------------|
| PTK29 | X | X | - |
| PTK6 | X | X | - |
| PTK7 | X | X | - |
| Measures | Damaged parts: Put sensor out of service and replace damaged parts resp. send sensor to ASM for repair | Loose mounting parts: Screw tight mounting parts with recommended torque, if applicable use bolt adhesive | Remove fouling |

4.2 Disposal

Disposal according to applicable government regulations.

5 Output specification

5.1 Digital output CANopen

| | | |
|--|-------------------------------|---|
| CANOP CANopen  | Communication profile | CANopen CiA 301, Slave |
| | Encoder profile | CiA 410, Profile „Inclinometer“ |
| | Configuration services | LSS, CiA Draft Standard 305 (Transmission rate, node ID) |
| | Error Control | Node guarding, Heartbeat, Emergency message |
| | Node ID | Adjustable via LSS or SDO, default: 127 |
| | PDO | 1 TxPDO, 0 RxPDO, no linking, static mapping |
| | PDO Modes | Event-/Time triggered, Remote-request, Sync cyclic/acyclic |
| | SDO | 1 Server, 0 Client |
| | Certified | yes |
| | Transmission rate | 125 kBit ... 1 Mbit, adjustable via LSS or SDO, default: 125 kBit |
| | Bus connection | M12 connector, 5 pin |
| | Bus, galvanic isolated | no |
| | Error Control Baudrate | 50 kBit/s ... 1 MBit/s configurable |
| | Transceiver | 24V-compliant, not isolated |
| | Internal termination resistor | 120 Ohm configurable |

| | | |
|-----------------------|-------------------------|---|
| Specifications | Excitation voltage | 8 ... 36 V DC |
| | Excitation current | 15 mA typical at 24 V DC 30 mA typical at 12 V DC, 100 mA max. |
| | Measuring rate | 0.5 kHz standard |
| | Stability (temperature) | ± 0,2° (-20 ... +40 °C) ± 0,4° (-40 ... +85 °C) |
| | Repeatability | 1 LSB |
| | Operating temperature | -40 ... +85 °C |
| | Protection | Reverse polarity, short circuit |
| | EMC | DIN EN 61326-1:2013 |

| Signal wiring | Output signals | Connector pin no. |
|--|----------------|-------------------|
| Connector M12, 5 pin  View to the sensor connector | Shield | 1 |
| | Excitation + | 2 |
| | GND | 3 |
| | CAN-H | 4 |
| | CAN-L | 5 |

CANopen – Set up (MCANOP)



Download

- A detailed specification of this interface can be downloaded from the ASM website:


www.asm-sensor.com/en/downloads.html > Configuration files

⚠ WARNING

Risk of injury by unexpected machine movement

- Change parameters only when machine is in a safe condition!
- Changing parameters may cause unexpected machine movement.
- Changing parameters may influence dependent parameters e.g. changing the resolution may have influence on position of CAM switches.
- Precautions have to be taken to avoid damage to human and machine parts!

5.2 Digital output SAE J1939

| | | |
|---|-------------------------------|--|
| CANJ1939 SAE J1939  | CAN Specification | ISO 11898, Basic and Full CAN 2.0 B extended message format with 29-bit identifier |
| | Transceiver | 24V-compliant, not isolated |
| | Communication profile | SAE J1939, 29-bit identifier |
| | Transmission rate | 250 kBit/s |
| | Internal termination resistor | 120 Ω |
| | Address | Default 247d, configurable |

| NAME - Unique device identifier | Name Fields | Remark | Field value | Size [Bit] | Byte order | Byte value | |
|---------------------------------|---------------------------|-------------------|-------------|------------|--------------|------------|------------|
| | Arbitrary Address Capable | No | 0 | 1 | Byte 8 (MSB) | 00h | |
| | Industry Group | Global | 0 | 3 | | | |
| | Vehicle System instance | | 0 | 4 | | | |
| | Vehicle System | Non specific | 7Fh | 7 | Byte 7 | FEh | |
| | Reserved | | 0 | 1 | | | |
| | Function | Non specific | FFh | 8 | Byte 6 | FFh | |
| | Function Instance | | 0 | 5 | Byte 5 | 00 | |
| | ECU Instance | | 0 | 3 | | | |
| | Manufacturer | Manufacturer Code | 145h | 11 | Byte 4 | 28h | |
| | | | | | | Byte 3 | A0h+n n |
| | | Identity Number | n..nh | 21 | | Byte 2 | nnh |
| | | | | | | Byte 1 | nnh |

| | | | |
|--|--------------------|-----------|--|
| Proprietary PGN - Manufacturer specific Parameter Group Numbers | Configuration data | PGN EFddh | Proprietary-A (PDU1 peer-to-peer) |
| | Process data | PGN FFnnh | Proprietary-B (PDU2 broadcast); nn Group Extension (PS) configurable |

| Specifications | | |
|----------------|-------------------------|--|
| | Excitation voltage | 8 ... 36 V DC |
| | Excitation current | 15 mA typical at 24 V DC 30 mA typical at 12 V DC, 100 mA max. |
| | Measuring rate | 0.5 kHz (asynchronous) |
| | Stability (temperature) | $\pm 0,2^\circ$ (-20 ... +40 °C) $\pm 0,4^\circ$ (-40 ... +85 °C) |
| | Repeatability | 1 LSB |
| | Operating temperature | -40 ... +85 °C |
| | Protection | Reverse polarity, short circuit |
| | EMV | DIN EN 61326-1:2013 |

| Signal wiring | Output signals | Connector pin no. |
|---|----------------|-------------------|
| Connector M12, 5 pin  View to the sensor connector | Shield | 1 |
| | Excitation + | 2 |
| | GND | 3 |
| | CAN-H | 4 |
| | CAN-L | 5 |

SAE J1939 – Set up (MCANJ1939)

**Download**

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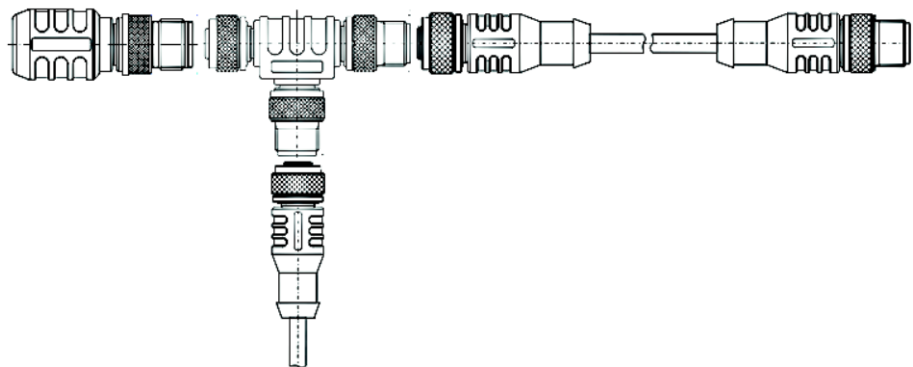
CAN-Bus wiring

Connect the device by a T-connector to the CAN trunk line. Total length of stubs should be minimized. Do not use single stub lines longer than 0.5 m. Connect terminating resistors 120 Ohm at both ends of the trunk line.

Termination resistor

T piece

CAN cable



sensor

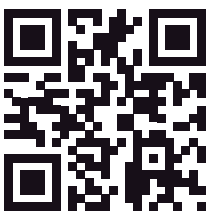
Reliability Parameters

| | | |
|-------------------------------|---|--------------------------------------|
| Models | PTK-CAN | |
| Interfaces | CANOP | CAN interface (CANopen) |
| | CANJ1939 | CAN interface (SAE J1939) |
| Reliability Parameters | Device type | B |
| | Life period electronics MTTF _D | 250 years |
| | Probability of failure electronics PFH (λ_{DU}) | 450 Fit |
| | Working life | 20 years |
| | Service and calibration interval | annually |
| Reference conditions | Supply Voltage U_B | $U_{Bref} = 24\text{ V}$ |
| | Reference temperature ϑ | $\vartheta_{ref} = 60^\circ\text{C}$ |
| Standards | Failure rate of electronic components (Siemens) | SN29500 |





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