



## WST85

Combined displacement and inclination sensor with measurement ranges up to 6,000 mm /  $\pm 180^\circ$



- Protection class up to IP67/IP69
- With magnetic absolute encoder
- With inclination sensor in MEMS technology
- High-performance PBT/stainless steel housing
- Redundant version available

### Product version



Digital output CANopen



WST85 - Combined displacement and inclination sensor  
Version with digital output CANopen

Specifications

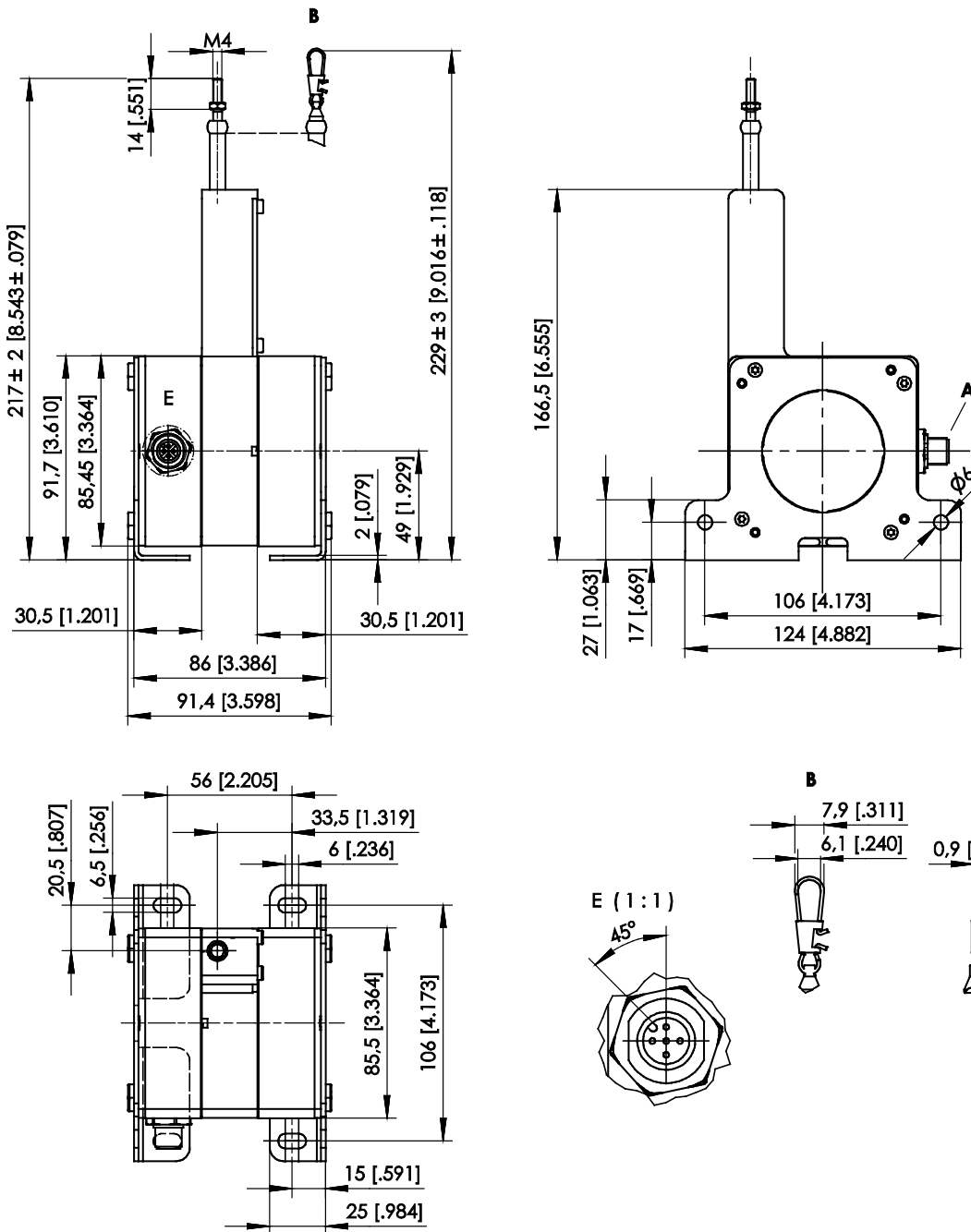
		Order options
Measurement range (position)	4000 / 5000 / 6000 mm	<b>1</b> 4000 / 5000 / 6000
Measurement range (inclination)	±180° with 1 axis	
Inclination axis	Inclination in X axis ≤±180°	
Resolution	setting via CAN Bus	
Output	Digital output CANopen Digital output CANopen redundant	<b>2</b> MCANOP MCANOPR
Linearity of position measurement	±0.10% f.s. (standard) ±0.05% f.s. (optional)	<b>3</b> L10 L05
Linearity of inclination measurement	0.05° (±30°) 0.1° (±60°) 0.2° (±180°)	
Sensing device (position measurement)	Magnetic absolute encoder	
Sensing device (inclination measurement)	MEMS device	
Material	PBT, stainless steel measuring cable: stainless steel	
Protection class	IP67/IP69	
Cable fixing	M4 cable fixing Cable clip	<b>4</b> M4 SB0
Connection	Connector M12, 5 pin	<b>5</b> M12/CAN
Shock	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks	
Vibration	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles	
Temperature range	-40 ... +85 °C	
Weight	approx. 1250 g	
EMV	DIN EN 61326-1:2013	

Order code

WST85 – **1** – **2** – **3** – **4** – **5**

Order example: WST85 – 6000 – MCANOP – L10 – M4 – M12/CAN

**Dimensions**  
WST85



A – Connector M12  
B – Option SB0

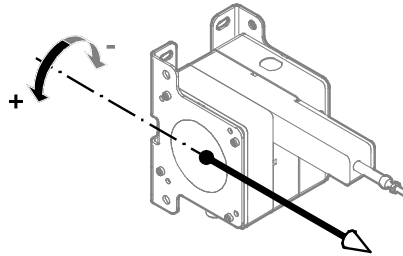
Dimensions in mm [inch]  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**Mounting options for inclination measurement for WST61 / WST85 sensors**

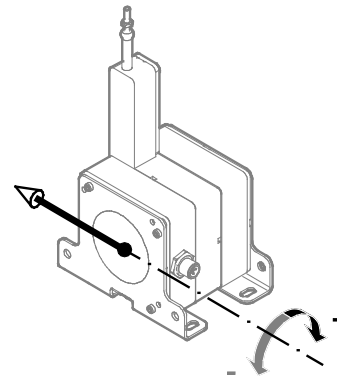
For CAN output, the mounting option can be set by the user via software.  
Sensor position as shown equals 0°.

**WST61 / WST85**

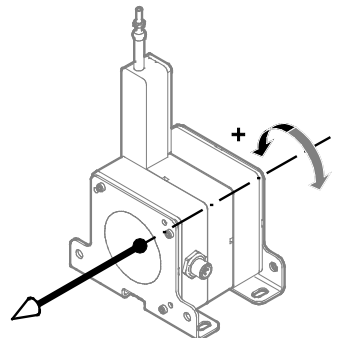
**Mounting option 1**



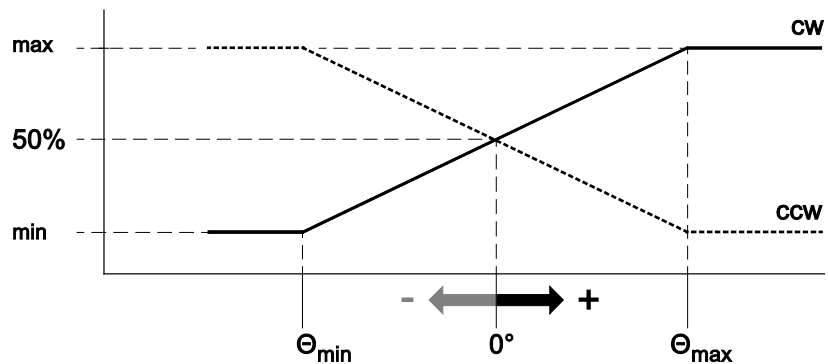
**Mounting option 2**




**Mounting option 3**



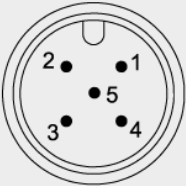
**Output signal**



## Digital interface CANopen

MCANOP, CANOPR	CAN specification	ISO 11898, Basic and Full CAN 2.0 B
	Communication profile	CANopen CiA 301 V 4.02, Slave
	Encoder profile	Encoder CiA 406 V 3.2
	Error Control	Node Guarding, Heartbeat, Emergency Message
	Node ID	Adjustable via LSS or SDO, default: 127
	PDO	3 TxPDO, 0 RxPDO, no linking, static mapping
	PDO Modes	Event-/Time triggered, Remote-request, Sync cyclic/acyclic
	SDO	1 Server, 0 Client
	CAM	8 cams
	Certified	Yes
	Transmission rate	50 kBit bis 1 Mbit, adjustable via LSS or SDO, default: 125 kBit
	Bus connection	M12 connector, 5 pin
	Integrated bus terminating resistor	120Ω adjustable by the customer
	Bus, galvanic isolated	no

Specifications	Excitation voltage	8 ... 36 V DC
	Excitation current	20 mA typical at 24 V DC 40 mA typical at 12 V DC 80 mA max.
	Measuring rate	0.5 kHz
	Stability (temperature)	±50 x 10 <sup>-6</sup> /°C f.s. (typical)
	Repeatability	1 LSB
	Operating temperature	See specification of the respective sensor
	Protection	Reverse polarity, short circuit
	Dielectric strength	1 kV (V AC, 50 Hz, 1 min.)
	EMC	EN 61326-1:2013

Signal wiring	Output signals	Connector pin no.
<b>Connector M12, 5 pin</b>  View to the sensor connector	Shield	1
	Excitation +	2
	GND	3
	CAN-H	4
	CAN-L	5

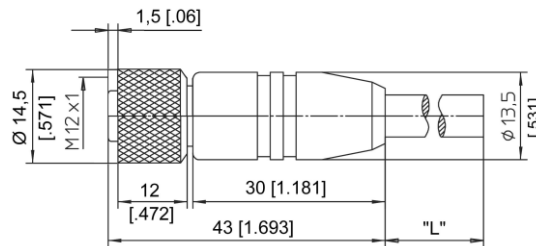
## Accessories

### Connector/bus cable M12, 5 pin CAN-Bus

The 5-lead shielded cable is supplied with a female 5 pin M12 connector at one end and a male 5 pin M12 connector at the other end.

Available lengths are 0.3 m, 2 m, 5 and 10 m.

Cable diameter: 6.7 ±0.2 mm



#### Order code

**KAB - xM - M12/5F/G - M12/5M/G - CAN**

IP69: **KAB - xM - M12/5F/G/69K - M12/5M/G/69K - CAN**

xM = length in m

### T-connector for bus cable M12, 5 pin CAN-Bus

#### Order code

**KAB - TCONN - M12/5M - 2M12/5F - CAN**



### Terminating resistor M12, 5 pin CAN-Bus

#### Order code

**KAB - RTERM - M12/5M/G - CAN**



#### Applicable for cable carriers

Maximum movement speed	3 m/s
Maximum acceleration	5 m/s <sup>2</sup>
Minimum bending radius	10 x cable diameter